

Safety and Security for Embedded Software Systems



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Project Coordination

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KANJAR

Key Facts

The next generation of networked embedded systems necessitates rapid prototyping and high performance while maintaining key qualities like trustworthiness and safety.

However, deployment of safety-critical embedded systems suffers from complex software toolchains and engineering processes.

Moreover, the current trend in autonomous systems relying on Machine Learning and Al applications in combination with fail-operational requirements renders the Verification and Validation of these new systems a challenging endeavor.



Objectives

- Provide holistic design methods and architectures that guarantee non-functional properties "by construction" throughout all phases of the software and system development lifecycle
- Improve development productivity and software quality with a reusable library of safety and security patterns, trusted HW/SW templates, and monitoring mechanisms

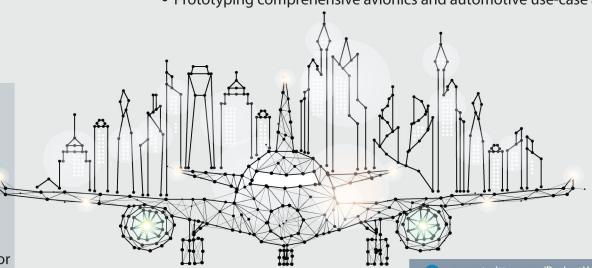


- Enable model-based design automation for trustworthy embedded software in critical environments
- Provide an interoperable, trustworthy and adaptive embedded HW/SW platform architecture that supports runtime platform health monitoring and self-healing capabilities
- Verification and validation of functional and non-functional requirements to show the effectiveness of the X-by-Construction paradigm
- Prototyping comprehensive avionics and automotive use-case application

Approach

XANDAR will deliver a **mature software toolchain** that fulfills the needs of the industry for rapid **prototyping of interoperable and autonomous embedded systems**.

Starting from a model-based system architecture,
XANDAR will leverage novel automatic
model synthesis and software
parallelization techniques to achieve specific
non-functional requirements setting the foundation for
a novel real-time, safety-, and
security-by-Construction (X-by-Construction) paradigm.



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